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PTO/SB/08A (08-03)

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**Complete if Known**

Application Number	10/083.705
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Filing Date	02/26/2002
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First Named Inventor	Choset
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Art Unit	3682
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Examiner Name	Van Pelt, Bradley
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Attorney Docket Number

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## U. S. PATENT DOCUMENTS

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## FOREIGN PATENT DOCUMENTS

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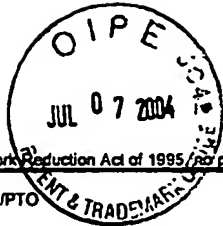
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STATEMENT BY APPLICANT**

(Use as many sheets as necessary)

Sheet

2

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Examiner Initials*	Cite No. <sup>1</sup>	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T <sup>2</sup>
		H. Choset, J. Luntz, E. Shammass, T. Rached, D. Hull and C. Dent Design and Motion Planning for Serpentine Robots Tokyo Institute of Technology Super Mechano, March 2-3, 2000	
		M. E. Rosheim Robot Wrist Actuators (Pages 52-89) John Wiley and Sons (February 1989)	
		E. Paljug, T. Ohm and S. Hayati. The JPL Serpentine Robot: a 12-DOF system for inspection Proc. of the 1995 IEEE/ICRA, Volume: 3, 1995	

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